

Subproject B2: “Experimental characterization, modell adaption and reliability: Micromechanical electrostatic field sensor for the detection of remanent charges”

- **Prof. Dr. Wolfram Dötzel**
- **Prof. Dr. Bernd Michel**, Fraunhofer IZM Berlin / Chemnitz

Author: Marian Hanf

Electrostatic driving and capacitive read out play an important role in MEMS. These systems consist of the micromechanical component and the driving and the detection electrodes, respectively. The electrodes are placed on insulating materials and in some cases they are coated with an insulating layer to prevent short circuit. It has often been observed that insulating materials carry charges for a long time after charging. The effect of these charges will be shown on the example of an acceleration sensor (Figure 1). It consists of a flexible suspended seismic mass, that is placed between two electrodes. To avoid an electrical short circuit in case of a contact of the mass and one electrode, spacers are deposited on both sides of the mass. The spacers are made of insulating material like SiO_2 or Si_3N_4 .

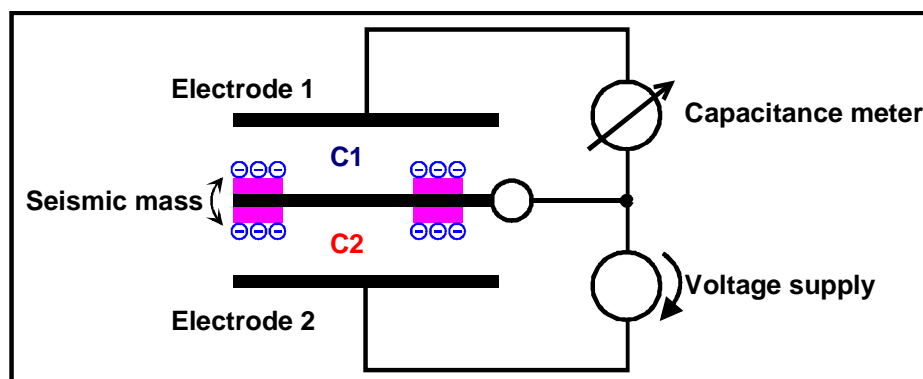


Figure 1: Scheme of an acceleration sensor and a characterization method

The measurement set up shown in Figure 1 is used to characterize the static deflection behavior of the sensor. Therefore a voltage is applied at one capacitance and the capacitance value of the opposite one is measured. Figure 2 shows two resulting voltage-capacitance-curves. They are shifted towards higher voltages. These offset voltages typically are caused by the presence of charges within the sensor. If the charge density changes the static deflection is changing too. Consequently, the characteristic of the acceleration sensor is influenced by charges. The reason for the presence of charges within the sensor is the manufacturing process. The aluminum electrodes are placed on glass wafers. A single crystalline silicon wafer is used to realize the seismic mass and its supporting bending beams. While assembling the wafers by an anodic bonding process voltages up to 400 V have to be applied. The consequential electrostatic force deflects the seismic mass towards the opposite electrode until it hits. To prevent sticking and an electrical short circuit the spacers are deposited on both sides of the seismic mass. Because the spacers have to be dielectric materials they carry charges deposited during the bonding process for a very long time.

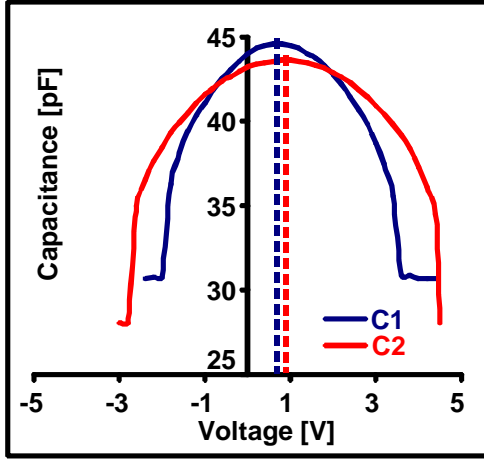


Figure 2: Measured voltage-capacitance-curve

To visualize the qualitative charge distribution on dielectric layers it is possible to take pictures using the scanning electron microscope (SEM). Because the yield of the secondary electrons depends on the electrical surface potential the charged areas become more light in case of negative charges and more dark in case of positive charges in relation to the not charged areas. To avoid an influence on the charges the electron beam parameters have to be chosen very carefully [2]. Techniques to measure the charge distribution are the Kelvin probe force microscopy (KPFM) [3], the electric scanning force microscopy (ESFM) [2], [3] and the electrostatic voltmeter[2].

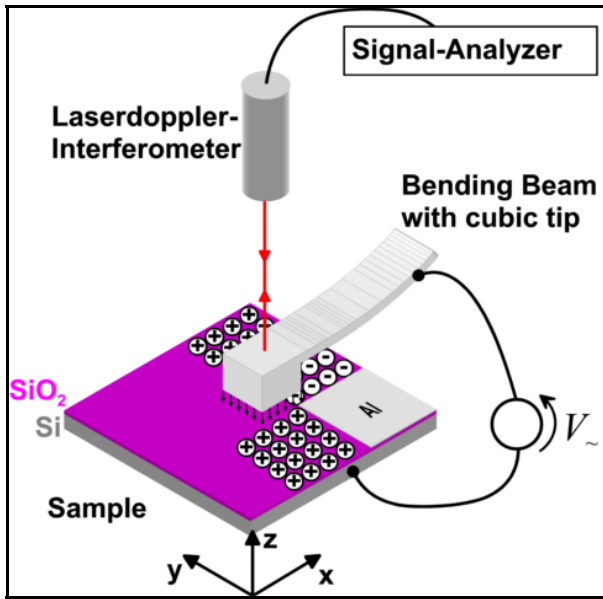


Figure 3: Scheme of the realized electrostatic field sensor

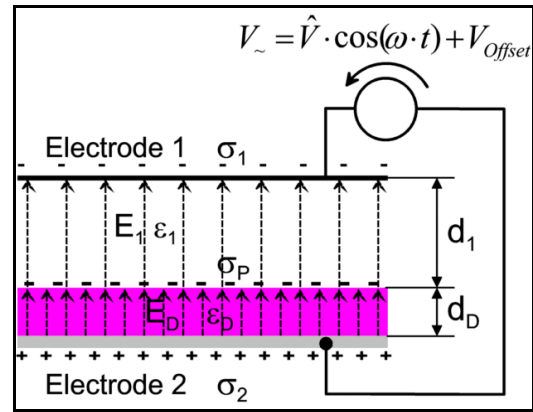


Figure 4: Simplified model of a plate capacitor with a dielectric layer

To characterize the behaviour of charges on dielectric layers in the region of driving or sensing electrodes of capacitive MEMS a measurement technique was developed that is related to the KPFM. Figure 3 shows a scheme of the realized electrostatic field sensor. It consists of a bending beam with a cubic tip whereby the lower surface is the sensing area with a size of about $50 \mu\text{m} \times 50 \mu\text{m}$. A sinusoidal voltage with the frequency ω and an adjustable offset voltage is applied between the sample and the beam. The resulting electrostatic force on the sensing area can be calculated on base of the simplified model shown in Figure 4. Because of the assumption of a homogeneous field (i.e., no electrostatic interaction with the adjacence) the plate capacitor has to be electrically neutral, i.e.

$$\sigma_1 + \sigma_2 + \sigma_p = 0 \quad (1)$$

Furthermore the Kirchoff's law is valid and the applied voltage divides into

$$V_{\sim} = E_1 \cdot d_1 + E_d \cdot d_d = \hat{V} \cdot \cos(\omega \cdot t) + V_{Offset} \quad (2)$$

Using the equations 1 and 2 and the commonly used equation for the electrostatic force the force on the sensing area (electrode 1) can be expressed as

$$F = -\frac{E_1 \cdot Q_1}{2} = \frac{1}{2} \varepsilon_0 \cdot \varepsilon_1 \cdot E_1^2 \cdot A \quad (3)$$

$$F = \frac{\varepsilon_0 \cdot \varepsilon_1 \cdot A}{2 \cdot \left(\frac{d_D \cdot \varepsilon_1}{\varepsilon_D} + d_1 \right)^2} \cdot \left[\frac{\hat{V}^2}{2} \cdot (1 + \cos(2 \cdot \omega \cdot t)) + 2 \cdot \hat{V} \cdot V_{Offset} \cdot \cos(\omega \cdot t) \right. \\ \left. + 2 \cdot \hat{V} \cdot \frac{d_D \cdot \sigma_P}{\varepsilon_0 \cdot \varepsilon_D} \cdot \cos(\omega \cdot t) + V_{Offset}^2 + \left(\frac{d_D \cdot \sigma_P}{\varepsilon_0 \cdot \varepsilon_D} \right)^2 + 2 \cdot V_{Offset} \cdot \frac{d_D \cdot \sigma_P}{\varepsilon_0 \cdot \varepsilon_D} \right] \quad (4)$$

Because of the linear spring stiffness of the bending beam the deflection of the tip is proportional to the force (4). Consequently, the beam deflects statically and oscillates at the frequencies ω and 2ω . The velocity of the motion is measured by the Laserdoppler-Interferometer. The signal analyzer calculates the FFT and integrates the signal to obtain the deflection amplitudes vs. frequency. Using the amplitude at the frequency ω the offset voltage V_{Offset} is controlled that way that equation 5 is fulfilled valid and the expression of the electrostatic force simplifies to equation 6. Now the beam oscillates only at the frequency 2ω and the deflection amplitude depends on d_1 . It is used to control the distance between sensing area and sample surface.

$$V_{Offset} = -\frac{d_D \cdot \sigma_P}{\varepsilon_0 \cdot \varepsilon_D} \quad (5)$$

$$F = \frac{\varepsilon_0 \cdot \varepsilon_1 \cdot A}{2 \cdot \left(\frac{d_D \cdot \varepsilon_1}{\varepsilon_D} + d_1 \right)^2} \cdot \frac{\hat{V}^2}{2} \cdot [1 + \cos(2 \cdot \omega \cdot t)] \quad (6)$$

The applied offset voltage is used to calculate the charge density at the surface of the dielectric layer in the range of the sensing area

$$\sigma_P = -\frac{V_{Offset} \cdot \varepsilon_0 \cdot \varepsilon_D}{d_D} \quad (7)$$

First measurement results are obtained with the realized setup shown in Figure 5. Figure 6a shows a top view of the scanned section of the sample. It consists of Si with 300 nm thermal SiO₂ and sputtered Al areas on top of the SiO₂. The Figures 6b-d show the measured charge distribution after charging the Al area to several voltages. While scanning over the Al area the charged voltages are obtained and even on the adjacent SiO₂ an offset voltage could be detected. This is caused by charges on the dielectric layer which might be deposited by ionization of the ambient air and the reorientation of dipoles (mainly water molecules) due to the high electric field on the sample surface.

This new measurement method will be used to characterize the development and the behavior of remanent charges on insulating materials in connection with electrode structures. The goal is to deduce design rules and the choice of materials for MEMS fabrication.

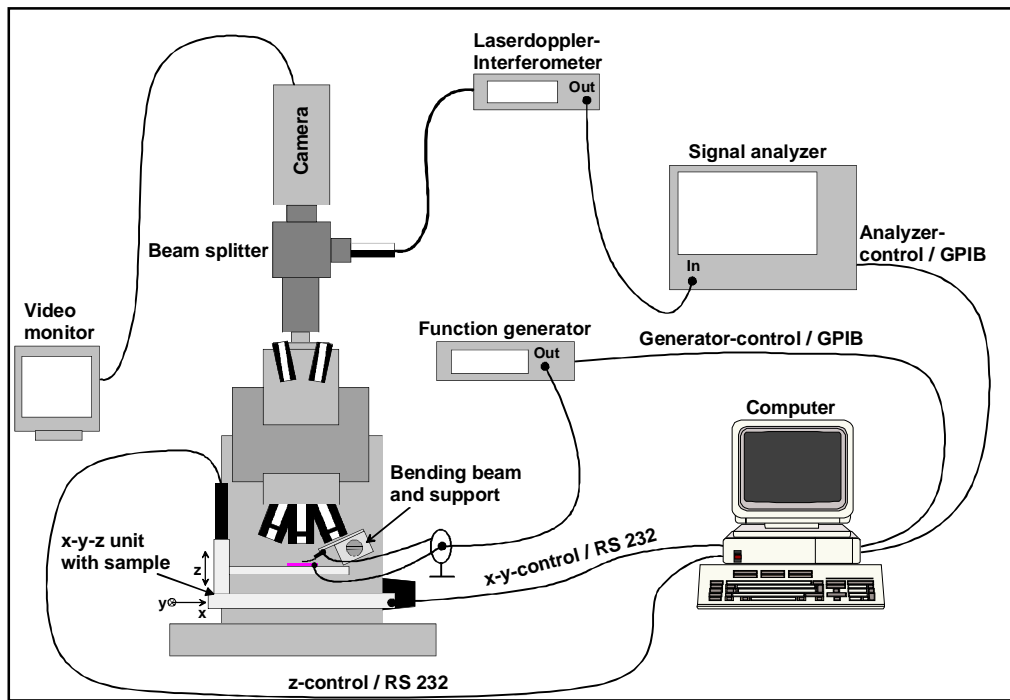


Figure 5: Realized measurement setup

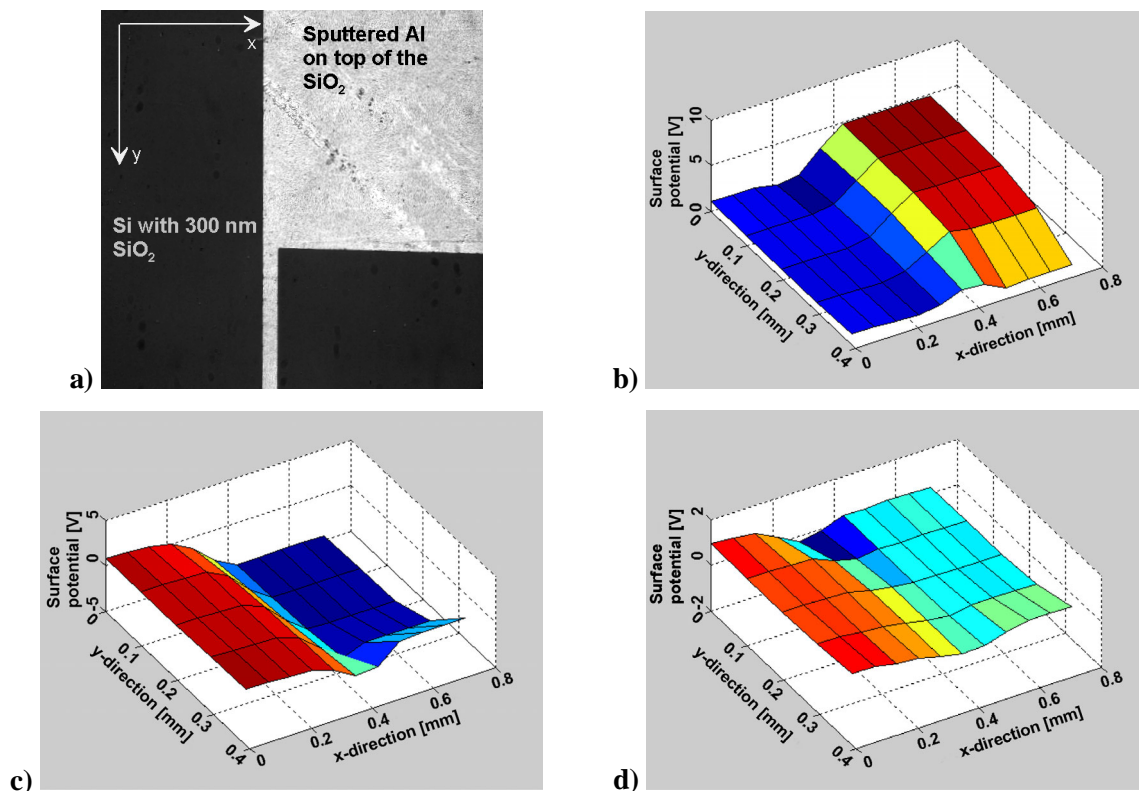


Figure 6: Measured charge distribution, a) used sample, b) Al charged to +5 V, c) Al charged to -5 V, d) Al charged to 0 V

References

- [1] Wibbeler, J. et al.: *Parasitic charging of dielectric surfaces in capacitive microelectromechanical systems (MEMS)*, Sensors and Actuators A 71, 1998, pp. 74-80
- [2] Hülz, H.: *Elektrische Charakterisierung der Oberfläche ferroelektrischer Schichten*, Dissertation, Dresden 1998
- [3] Müller, F.: *Simultane Messung elektrischer Größen mit der Rastersondenmikroskopie*, Dissertation, Chemnitz 1997